

Sample Solutions for Sample Questions 15.

$$1. \quad I_4 = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

$$A = \begin{pmatrix} 0 & 1 & & \\ & 0 & 1 & \\ & & 0 & 1 \\ & & & 0 \end{pmatrix}$$

$$A^2 = \begin{pmatrix} 0 & 0 & 1 & \\ & 0 & 0 & 1 \\ & & 0 & 0 \\ & & & 0 \end{pmatrix}$$

$$A^3 = \begin{pmatrix} 0 & 0 & 0 & 1 \\ & 0 & 0 & 0 \\ & & 0 & 0 \\ & & & 0 \end{pmatrix}$$

$$A^4 = 0.$$

$$\text{Suppose } a_0 I_4 + a_1 A + a_2 A^2 + a_3 A^3 = 0$$

$$\begin{pmatrix} a_0 & a_1 & a_2 & a_3 \\ & a_0 & a_1 & a_2 \\ & & a_0 & a_1 \\ & & & a_0 \end{pmatrix} = 0 \Rightarrow a_0 = a_1 = a_2 = a_3 = 0.$$

$\Rightarrow \{I_4, A, A^2, A^3\}$ is linearly independent.

$$\text{But } A^4 = 0.$$

$\Rightarrow p(A) \neq 0$ if $\deg p(x) \leq 3$.

$p(A) = 0$ if $p(x) = x^4$. \Rightarrow min poly is $p(x) = x^4$.

Similarly, the min poly of $A + \lambda I_4$
is $p(x) = (x - \lambda)^4$.

2.

$$I = \begin{pmatrix} 1 & & \\ & 1 & \\ & & 1 \end{pmatrix}$$

$$A = \begin{pmatrix} 2 & & \\ & 2 & \\ & & 3 \\ & & & 3 \end{pmatrix}$$

$$A^2 = \begin{pmatrix} 4 & & \\ & 4 & \\ & & 9 \\ & & & 9 \end{pmatrix}$$

Solve $a_0 I + a_1 A + A^2 = O$.

$$\begin{pmatrix} a_0 + 2a_1 + 4 & & & \\ & a_0 + 2a_1 + 4 & & \\ & & a_0 + 3a_1 + 9 & \\ & & & a_0 + 3a_1 + 9 \end{pmatrix} = O.$$

$$\Rightarrow \begin{cases} a_0 + 2a_1 = -4 \\ a_0 + 3a_1 = -9 \end{cases} \Rightarrow \begin{cases} a_0 = -6 \\ a_1 = -5 \end{cases}$$

So $p(A) = 0$ when $p(x) = x^2 - 5x + 6 = (x-2)(x-3)$.

(You may check $p(A) \neq 0$ if $\deg p(x) \leq 1$.)

So min poly is $p(x) = x^2 - 5x + 6$.

$$3. \quad f' = \begin{pmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial z} \end{pmatrix} = \begin{pmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow \det(f') = r \cos^2 \theta + r \sin^2 \theta = r$$

$$4. \quad f' = \begin{pmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \phi} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \phi} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \phi} \end{pmatrix} = \begin{pmatrix} \sin \phi \cos \theta & -r \sin \phi \sin \theta & r \cos \phi \cos \theta \\ \sin \phi \sin \theta & r \sin \phi \cos \theta & r \cos \phi \sin \theta \\ \cos \phi & 0 & -r \sin \phi \end{pmatrix}$$

~~$$\Rightarrow \det(f') = -r \sin \phi (\sin \phi \cos \theta r \sin \phi \cos \theta + r \sin \phi \sin \theta \sin \phi \sin \theta)$$~~

$$\Rightarrow \det(f') = -r \sin \phi \cdot \det \begin{pmatrix} \sin \phi \cos \theta & -r \sin \phi \sin \theta \\ \sin \phi \sin \theta & r \sin \phi \cos \theta \end{pmatrix}$$

$$+ \cos \phi \cdot \det \begin{pmatrix} -r \sin \phi \sin \theta & r \cos \phi \cos \theta \\ r \sin \phi \cos \theta & r \cos \phi \sin \theta \end{pmatrix}$$

$$= -r^2 (\sin \phi)^3 \det \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} + r^2 (\cos \phi)^2 \sin \phi \det \begin{pmatrix} -\sin \theta & \cos \theta \\ \cos \theta & \sin \theta \end{pmatrix}$$

$$= -r^2 \sin^3 \phi - r^2 (\cos \phi)^2 \sin \phi$$

$$= -r^2 \sin \phi (\sin^2 \phi + \cos^2 \phi) = -r^2 \sin \phi$$

$$5. \quad f(\vec{v}) = A\vec{v}.$$

That is

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

$$\Rightarrow \begin{cases} y_1 = 1x_1 + 2x_2 + 3x_3 \\ y_2 = 4x_1 + 5x_2 + 6x_3 \end{cases}$$

$$f' = \begin{pmatrix} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_1}{\partial x_2} & \frac{\partial y_1}{\partial x_3} \\ \frac{\partial y_2}{\partial x_1} & \frac{\partial y_2}{\partial x_2} & \frac{\partial y_2}{\partial x_3} \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}.$$

So $f' = A$.

In fact, if $f(\vec{v}) = A\vec{v}$,
then $f' = A$.

6.

Since $f(x)$ is over \mathbb{C} ,

by the Fundamental Theorem of Algebra,

we may write

$$f(x) = (x-\lambda_1) \cdots (x-\lambda_n)$$

($\lambda_1, \dots, \lambda_n$ might repeat.)

① Suppose $\lambda_1, \dots, \lambda_n$ contains a multiple root.

Without loss of generality, assume $\lambda_1 = \lambda_2$.

$$\text{Then } f'(x) = \frac{f(x)}{(x-\lambda_1)} + \frac{f(x)}{(x-\lambda_2)} + \cdots + \frac{f(x)}{x-\lambda_n}$$

Note that $\frac{f(x)}{x-\lambda_1}$ contains the factor $x-\lambda_2$

and $\frac{f(x)}{x-\lambda_i}$ has factors $x-\lambda_1$ and $x-\lambda_2$ for $i=3, \dots, n$.

\Rightarrow So $\lambda_1 = \lambda_2$ is a common root for $f(x)$ and $f'(x)$.

② Suppose $\lambda_1, \dots, \lambda_n$ are all distinct.

$$\text{Then } f'(x) = \frac{f(x)}{x-\lambda_1} + \frac{f(x)}{x-\lambda_2} + \cdots + \frac{f(x)}{x-\lambda_n}$$

Compute $f'(\lambda_1) = (\lambda_1-\lambda_2)(\lambda_1-\lambda_3) \cdots (\lambda_1-\lambda_n) + 0 + 0 + \cdots + 0 \neq 0$.

Similarly, $f'(\lambda_2) \neq 0, \dots, f'(\lambda_n) \neq 0$.

\Rightarrow $f(x)$ and $f'(x)$ have no common root.

