

Sample Solutions for Sample Questions 7

1. Equivalently, the condition says

$$\vec{r}_j - \sum_{i \neq j} c_i \vec{r}_i = \vec{0},$$

Therefore, $A \xrightarrow[\text{for all } i \neq j]{-c_i \vec{r}_i + \vec{r}_j} B$

and the j -th row of B is zero.

$$\Rightarrow \det(B) = 0.$$

Since $\underline{-c_i \vec{r}_i + \vec{r}_j}$ does not change the determinant,

$$\det(A) = \det(B) = 0.$$

2.

$$\det(A) = \det \begin{pmatrix} 1 & a & a^2 & a^3 \\ 0 & b-a & b^2-a^2 & b^3-a^3 \\ 0 & c-a & c^2-a^2 & c^3-a^3 \\ 0 & d-a & d^2-a^2 & d^3-a^3 \end{pmatrix}$$

$$= (b-a)(c-a)(d-a) \cdot \det \begin{pmatrix} 1 & a & a^2 & a^3 \\ 0 & 1 & b+a & b^2+ab+a^2 \\ 0 & 1 & c+a & c^2+ac+a^2 \\ 0 & 1 & d+a & d^2+ad+a^2 \end{pmatrix}$$

$$= (b-a)(c-a)(d-a) \cdot \det \begin{pmatrix} 1 & a & a^2 & a^3 \\ & 1 & b-a & b^2+ab+a^2 \\ 0 & c-b & c^2-b^2+ac-ab & \\ 0 & d-b & d^2-b^2+ad-ab & \end{pmatrix}$$

$$= (b-a)(c-a)(d-a)(c-b)(d-b) \cdot \det \begin{pmatrix} 1 & a & a^2 & a^3 \\ & 1 & b-a & b^2+ab+a^2 \\ & & 1 & c+b+a \\ & & & 1 & d+b+a \end{pmatrix}$$

$$= (b-a)(c-a)(d-a)(c-b)(d-b) \cdot \det \begin{pmatrix} 1 & a & a^2 & a^3 \\ & 1 & b-a & b^2+ab+a^2 \\ & & 1 & c+b+a \\ & & & 0 & d-c \end{pmatrix}$$

$$= (b-a)(c-a)(d-a)(c-b)(d-b)(d-c)$$

4.

$$\det \begin{pmatrix} a & b & c & d \\ e & f & g & h \\ i & j & k & l \\ m & n & o & p \end{pmatrix} =$$

$$\begin{aligned} & afkp - afplo - agjp + agln + ahjo - ahkn \\ = & -bekp + belo + bgip - bglm - bhia + bhkm \\ & + cejp - celn - cfip + cflm + chia - chjm \\ & - dejo + dekn + dfio - dfkm - dgin + dgjm. \end{aligned}$$

5. $\phi = (2, 3, 4, 5, 1) \quad \phi^{-1} = (5, 1, 2, 3, 4)$

$$P_\phi = \begin{pmatrix} & & & & \\ & & & & \\ & & & & \\ & & & & \\ 1 & & & & \end{pmatrix} \quad P_{\phi^{-1}} = \begin{pmatrix} 1 & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & 1 \end{pmatrix}$$

P_ϕ^T

$$\det(P_\phi) = \det(P_\phi^T) = 1.$$

6. Suppose A is singular.

$$\Rightarrow \text{rank}(A) < n$$

$$\Rightarrow \text{Colspace}(A) \subsetneq \mathbb{R}^n$$

\leftarrow a subset, but not ~~equal~~ equal.

Observe that

$$\begin{aligned} \text{Colspace}(AB) &= \{ \underline{ABx} \mid x \in \mathbb{R}^n \} \\ &\quad \leftarrow \text{看成一個向量} \\ &\subseteq \{ Ax \mid x \in \mathbb{R}^n \} = \text{Colspace}(A) \subsetneq \mathbb{R}^n. \end{aligned}$$

$$\Rightarrow \text{rank}(AB) < n$$

$$\Rightarrow AB \text{ is singular.}$$

Thus, A is singular $\Rightarrow AB$ is singular.

$$\text{Therefore } \det(A) = 0 \Rightarrow \det(AB) = 0.$$

When A is singular,

$$\det(AB) = 0 = \det(A) \cdot \det(B).$$

7.

By Problem 6,

$$\det(AB) = \det(A)\det(B) = 0 \text{ when } A \text{ is singular.}$$

Suppose A is nonsingular,

Then the reduced echelon form of A is I ,

and there are elementary matrices E_1, \dots, E_k

$$\text{so that } E_k \dots E_1 A = I \Leftrightarrow A = E_1^{-1} \dots E_k^{-1}$$

$$\text{and } \det(A) = \det(E_1^{-1}) \dots \det(E_k^{-1})$$

also elementary matrices.

Thus

$$AB = E_1^{-1} \dots E_k^{-1} \cdot B$$

This means AB is obtained from B by

applying row operations corresponding to $E_k^{-1}, \dots, E_1^{-1}$.

By definition of determinant,

$$\det(AB) = \det(E_1^{-1}) \dots \det(E_k^{-1}) \cdot \det(B)$$

$$= \det(A) \cdot \det(B)$$