

Sample Questions 7

1. Let

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \mathbf{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

Apply the Gram–Schmidt algorithm to the set $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ and obtain an orthogonal basis $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ for the space $\mathbb{R}^3 = \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$.

2. Following the previous problem, normalize the vectors $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ to obtain an orthonormal basis $\{\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2, \hat{\mathbf{u}}_3\}$. Going through all the calculation, you should be able to find

$$\mathbf{v}_1 = r_{1,1}\hat{\mathbf{u}}_1 + r_{2,1}\hat{\mathbf{u}}_2 + r_{3,1}\hat{\mathbf{u}}_3,$$

$$\mathbf{v}_2 = r_{1,2}\hat{\mathbf{u}}_1 + r_{2,2}\hat{\mathbf{u}}_2 + r_{3,2}\hat{\mathbf{u}}_3,$$

$$\mathbf{v}_3 = r_{1,3}\hat{\mathbf{u}}_1 + r_{2,3}\hat{\mathbf{u}}_2 + r_{3,3}\hat{\mathbf{u}}_3.$$

Let

$$\mathbf{A} = \begin{bmatrix} | & | & | \\ \mathbf{v}_1 & \mathbf{v}_2 & \mathbf{v}_3 \\ | & | & | \end{bmatrix}, \mathbf{Q} = \begin{bmatrix} | & | & | \\ \hat{\mathbf{u}}_1 & \hat{\mathbf{u}}_2 & \hat{\mathbf{u}}_3 \\ | & | & | \end{bmatrix}$$

and $\mathbf{R} = [r_{i,j}]$. Verify that $\mathbf{A} = \mathbf{QR}$ such that \mathbf{Q} is an orthogonal matrix and \mathbf{R} is an upper triangular matrix.

3. Let $V = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} : x + y + z = 0 \right\}$ be a vector space. Find an orthogonal basis for V .

4. Recall that an $n \times n$ matrix is an orthogonal matrix if $\mathbf{A}^\top \mathbf{A} = \mathbf{A} \mathbf{A}^\top = \mathbf{I}_n$. Show that for every vector $\mathbf{v} \in \mathbb{R}^n$, $\text{Rep}_{\mathcal{B}}(\mathbf{v}) = \mathbf{A}^\top \mathbf{v}$, where \mathcal{B} is the orthonormal basis formed by the columns of \mathbf{A} .

5. Let

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 5 & 4 \\ 1 & 3 & 4 & 5 \\ 1 & 3 & 6 & 6 \end{bmatrix}.$$

Use the definition (Four.I.2.1 of the textbook) to find $\det(\mathbf{A})$.

6. Find the determinant of the (row) elementary matrix of each type. Show that $\det(\mathbf{E}^{-1}) = \det(\mathbf{E})^{-1}$ if \mathbf{E} is an elementary matrix.

7. By Gaussian elimination, if a matrix \mathbf{A} has the reduced echelon form \mathbf{R} , then we have $\mathbf{E}_k \cdots \mathbf{E}_1 \mathbf{A} = \mathbf{R}$ or $\mathbf{A} = \mathbf{E}_1^{-1} \cdots \mathbf{E}_k^{-1} \mathbf{R}$, where \mathbf{E}_i 's are elementary matrices. Check that

$$\det(\mathbf{A}) = \det(\mathbf{E}_1^{-1}) \cdots \det(\mathbf{E}_k^{-1}) \det(\mathbf{R}).$$

Use this to show that $\det(\mathbf{A}) \neq 0$ if and only if \mathbf{A} is invertible.