Zero forcing and its applications

Jephian C.-H. Lin

Department of Mathematics and Statistics, University of Victoria

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$$2x +3y -z = 4x -y +2z = 3-3x +2y +z = 2$$

Hard to know if the solution exists, or if the solution is unique.

I don't want to solve it!

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$$2x +y -z = 1$$

$$2y = 4$$

$$+2y +3z = 7$$

Easy to see y = 2, then z = 1, and then x = 0. Easy to know the solution exists and is unique.

l like it! 😊

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Main philosophy

$$2x + y + 3z = 7$$
$$x = 1, y = 2 \implies z = 1$$

In a linear equation, if all but one variable are known, then this remaining variable is also known.

$$2x + y + 3z = 0$$
$$x = 0, y = 0 \implies z = 0$$

In a homogeneous linear equation, if all but one variable are zero, then this remaining variable is also zero.

1.
$$x +z +u = 0$$

2. $y +z = 0$
3. $x +y +z +w +u = 0$
4. $z +w = 0$
5. $x +z +u = 0$

Given information: x = y = 0. Then

$$2. \implies z = 0,$$

$$4. \implies w = 0,$$

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Given information: x = y = 0. Then

$$\begin{array}{ll} 2. \implies z = 0, \\ 4. \implies w = 0, \\ 3. \implies u = 0. \end{array}$$

As long as the red terms has nonzero coefficients and the orange terms are zero, the same argument always works.

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Application to algebra

Find the inverse of a formal power series.

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Application to algebra

Find the inverse of a formal power series.

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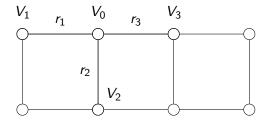
Application to algebra

Find the inverse of a formal power series.

A formal power series has an inverse if and only if the constant term is nonzero.

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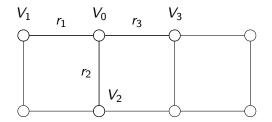
$$\frac{1}{r_1}(V_0 - V_1) + \frac{1}{r_2}(V_0 - V_2) = \frac{1}{r_3}(V_3 - V_0) + \epsilon V_0$$



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$$\frac{1}{r_1}(V_0 - V_1) + \frac{1}{r_2}(V_0 - V_2) = \frac{1}{r_3}(V_3 - V_0) + \epsilon V_0$$
$$\frac{1}{r_1}V_1 + \frac{1}{r_2}V_2 + \frac{1}{r_3}V_3 + (\epsilon - \frac{1}{r_1} - \frac{1}{r_2} - \frac{1}{r_3})V_0 = 0$$



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Zero forcing

$$\frac{1}{r_1}V_1 + \frac{1}{r_2}V_2 + \frac{1}{r_3}V_3 + (\epsilon - \frac{1}{r_1} - \frac{1}{r_2} - \frac{1}{r_3})V_0 = 0$$

$$a_1V_1 + a_2V_2 + a_3V_3 + a_0V_0 = 0$$
nonzero
$$V_1 \quad r_1 \quad V_0 \quad r_3 \quad V_3$$

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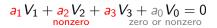
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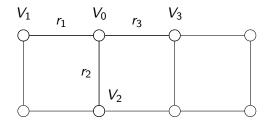
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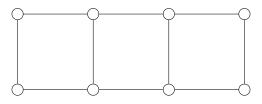
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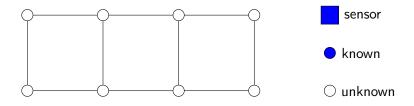


The conservation law leads to a linear equation on each node; itself and its neighbours represent the variables.

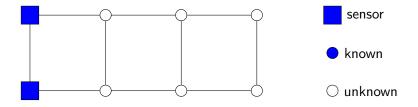




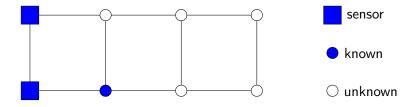
- Each vertex represents a linear equation; variables are itself and its neighbors (closed neighbourhood).
- If in a closed neighbourhood, all but one voltages are known, then this remaining one are also known.



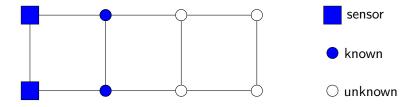
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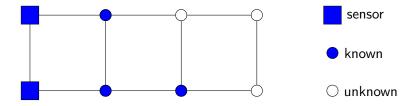
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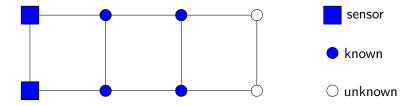


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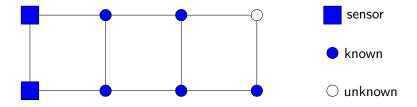
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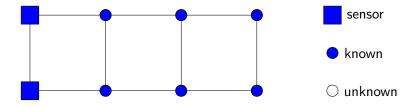


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Model by graphs and matrices

- A electronic circuit can be represented by a graph; each vertex represents a node, and each edge represents a connection.
- The linear equations can be recorded into a matrix; each row represents a equation, and each column represents an unknown voltage.
- This is a symmetric matrix where rows and columns are both indexed by the vertices.

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- This is a symmetric matrix where rows and columns are both indexed by the vertices.

Let G be a simple graph on n vertices. The family $\mathcal{S}(G)$ consists of all $n \times n$ real symmetric matrix $M = [M_{i,j}]$ with

$$\begin{cases} M_{i,j} = 0 & \text{if } i \neq j \text{ and } \{i,j\} \text{ is not an edge,} \\ M_{i,j} \neq 0 & \text{if } i \neq j \text{ and } \{i,j\} \text{ is an edge,} \\ M_{i,j} \in \mathbb{R} & \text{if } i = j. \end{cases}$$
$$\mathcal{S}(\circ \circ \circ \circ) \ni \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix}, \begin{bmatrix} 2 & 0.1 & 0 \\ 0.1 & 1 & \pi \\ 0 & \pi & 0 \end{bmatrix}, \cdots$$

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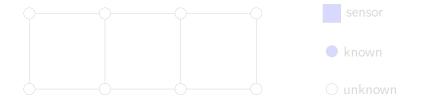
Zero forcing

Zero forcing

Zero forcing process:

- Start with a given set of blue vertices (sensors).
- If for some x, the closed neighbourhood N_G[x] are all blue except for one vertex y and y ≠ x, then y turns blue.

An initial blue set that can make the whole graph blue is called a zero forcing set. The zero forcing number Z(G) of a graph G is the minimum size of a zero forcing set.



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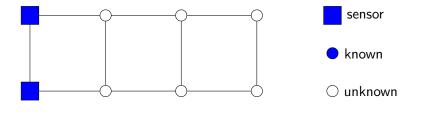
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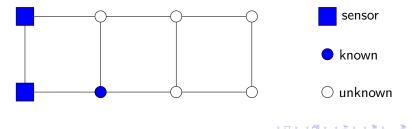
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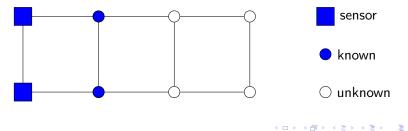
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How to deploy the sensors?

Any zero forcing set is a good deployment of sensors that can monitor the whole graph.

The zero forcing number is the minimum number of sensors required.

Zero forcing sets suggest a good deployment before knowing the details of the network.

Many studies are done on zero forcing and its variation power domination.

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Proposition (Kenter and L 2018)

Let G be a graph on the vertex set V. The following are equivalent:

- 1. B is a zero forcing set.
- 2. For any $A \in S(G)$, the columns corresponding to $V \setminus B$ hides a lower triangular matrix.
- 3. For any $A \in S(G)$, the columns corresponding to $V \setminus B$ are linearly independent.

Theorem (AIM Work Group 2008)

Let G be a graph on n vertices. For any matrix $A \in S(G)$, $n - Z(G) \leq \operatorname{rank}(A)$.

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Same argument works for non-symmetric matrices.

- When more information are known on the matrices, the design of the zero forcing process can be improved.
- For example, nonnegative matrices, zero diagonal entries, or nonzero diagonal entries.
- They all follow the same philosophy.
- Zero forcing is related to the minimum rank problem (Math), quantum control (Physics), building logic circuit (Physics), the graph searching problem (ComS).

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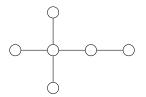
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Domination number and zero forcing

Zero forcing

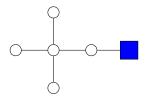
Color change rule:

If for some x, the closed neighbourhood $N_G[x]$ are all blue except for one vertex y, then y turns blue.



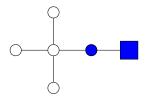
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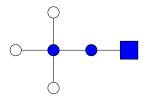
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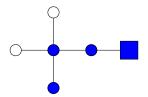
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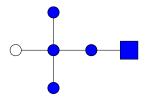
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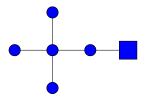
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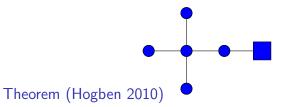
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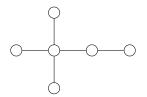
 $Z_{i}(G) =$ minimum size of a zero forcing set.



Let G be a graph on n vertices. Then $n - Z_{\ell}(G) \leq \operatorname{rank}(A)$ for any $A \in S(G)$ with nonzero diagonal entries.

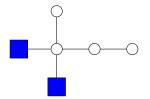
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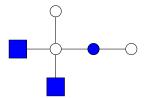
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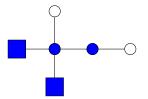
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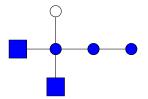
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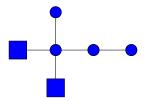
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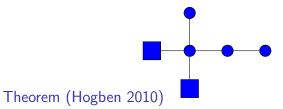
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 $Z_{-}(G) =$ minimum size of a zero forcing set.



Let G be a graph on n vertices. Then $n - Z_{-}(G) \le \operatorname{rank}(A)$ for any $A \in S(G)$ with zero diagonal entries.

Domination number

Let G be a graph. The domination number $\gamma(G)$ is the minimum cardinality of a set X such that

$$\bigcup_{x\in X} N_G[x] = V(G).$$

The total domination number $\gamma^t(G)$ is the minimum cardinality of a set X such that

$$\bigcup_{x\in X}N_G(x)=V(G).$$

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Greedy algorithm

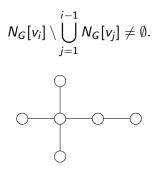
- Greedy algorithm follows the problem solving heuristic of making the locally optimal choice at each stage with the hope of finding a global optimum.
- Greedy algorithm for domination number: When X are chosen and not yet dominate the whole graph, pick a vertex v such that

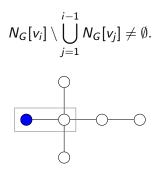
 $N_G[v] \setminus \bigcup_{x \in X} N_G[x] \neq \emptyset.$

Greedy algorithm

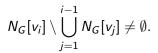
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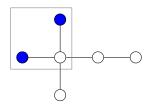
$$N_G[v] \setminus \bigcup_{x \in X} N_G[x] \neq \emptyset.$$





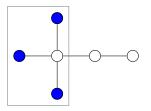
The Grundy domination number $\gamma_{gr}(G)$ is the length of the longest sequence (v_1, v_2, \ldots, v_k) such that



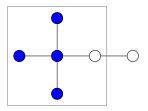


Zero forcing

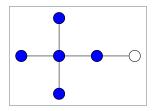
$$N_G[v_i] \setminus \bigcup_{j=1}^{i-1} N_G[v_j] \neq \emptyset.$$



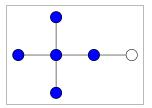
$$N_G[v_i] \setminus \bigcup_{j=1}^{i-1} N_G[v_j] \neq \emptyset.$$



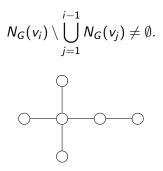
$$N_G[v_i] \setminus \bigcup_{j=1}^{i-1} N_G[v_j] \neq \emptyset.$$



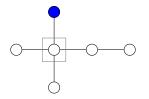
$$N_G[v_i] \setminus \bigcup_{j=1}^{i-1} N_G[v_j] \neq \emptyset.$$



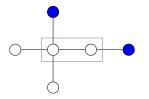
So
$$\gamma_{\rm gr}(G) = 5$$
.



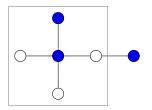
$$N_G(v_i)\setminus \bigcup_{j=1}^{i-1}N_G(v_j)\neq \emptyset.$$



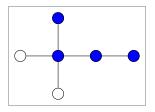
$$N_G(v_i)\setminus \bigcup_{j=1}^{i-1}N_G(v_j)\neq \emptyset.$$



$$N_G(v_i) \setminus \bigcup_{j=1}^{i-1} N_G(v_j) \neq \emptyset.$$

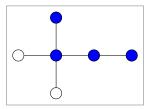


$$N_G(v_i)\setminus \bigcup_{j=1}^{i-1}N_G(v_j)
eq \emptyset.$$



The Grundy total domination number $\gamma_{gr}^t(G)$ is the length of the longest sequence (v_1, v_2, \ldots, v_k) such that

$$N_G(v_i)\setminus \bigcup_{j=1}^{i-1}N_G(v_j)
eq \emptyset.$$



So
$$\gamma_{\rm gr}^t(G) = 4$$
.

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Grundy domination number, zero forcing number, and the rank bound

Theorem (L 2017)

Let G be a graph on n vertices. Then

$$\gamma_{ ext{gr}}(\mathsf{G}) = \mathsf{n} - \mathsf{Z}_{\acute{\ell}}(\mathsf{G}) ext{ and } \gamma^t_{ ext{gr}}(\mathsf{G}) = \mathsf{n} - \mathsf{Z}_-(\mathsf{G}).$$

Therefore,

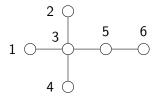
$$\gamma_{
m gr}(G) \leq {
m rank}(A)$$

for any $A \in \mathcal{S}(G)$ with diagonal entries all nonzero; and

 $\gamma_{
m gr}^t(G) \leq
m rank(A)$

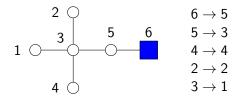
for any $A \in \mathcal{S}(G)$ with zero diagonal.

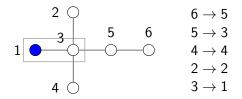
Key: Reverse the forcing process!

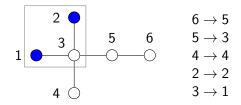


Zero forcing

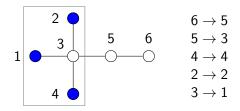
23/26



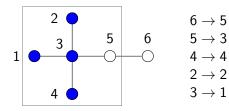


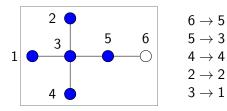


Key: Reverse the forcing process!

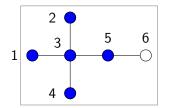


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Key: Reverse the forcing process!



$$\begin{array}{c} 6 \rightarrow 5 \\ 5 \rightarrow 3 \\ 4 \rightarrow 4 \\ 2 \rightarrow 2 \\ 3 \rightarrow 1 \end{array}$$

Thank you!

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http://arxiv.org/abs/1709.08740. (under review).



J. C.-H. Lin.

Zero forcing number, Grundy domination number, and their variants.

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http://arxiv.org/abs/1706.00798.
(under review).
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