

Graphs whose distance matrices have the same determinant

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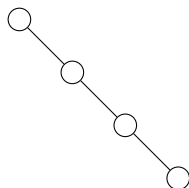
Joint work with Yen-Jen Cheng
(National Chiao Tung University).

Distance matrix

- ▶ Let G be a **connected** graph. The **distance** between two vertices i and j is the length of the shortest path connecting them, denoted as $\text{dist}_G(i, j)$.
- ▶ The **distance matrix** of G is

$$\mathcal{D}(G) = [\text{dist}_G(i, j)].$$

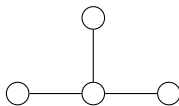
- ▶ For short, let $\text{det}_{\mathcal{D}}(G) = \det(\mathcal{D}(G))$.



$$\begin{bmatrix} 0 & 1 & 2 & 3 \\ 1 & 0 & 1 & 2 \\ 2 & 1 & 0 & 1 \\ 3 & 2 & 1 & 0 \end{bmatrix}$$



$$\det_{\mathcal{D}}(P_4) = -12$$



$$\det_{\mathcal{D}}(K_{1,3}) = -12$$

Theorem (Graham and Pollak 1971)

For every tree T on n vertices,

$$\det_{\mathcal{D}}(T) = (-1)^{n-1}(n-1)2^{n-2}.$$

History

- ▶ Graham and Pollak 1971: $\det_{\mathcal{D}}(T)$ of a tree T **only depends on n** . [Yan and Yeh gave a simpler proof in 2006.]
- ▶ Graham, Hoffman, and Hosoya 1977: $\det_{\mathcal{D}}(G)$ **only depends on its blocks**, but not how blocks attached together.
- ▶ Bapat, Kirkland, and Neumann: **weighted** distance matrix of a tree.
- ▶ Bapat, Lal, and Pati; Yan and Yeh: **q -analog** and the **q -exponential** distance matrix of a tree.

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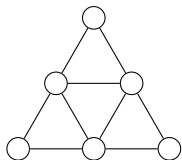
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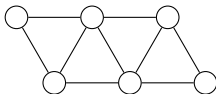
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How about graphs without a cut vertex?

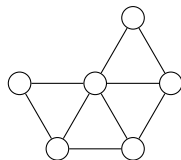
How about k -trees?



$$\det_{\mathcal{D}}(G_1) = -8$$

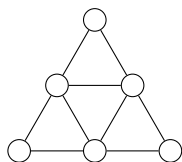


$$\det_{\mathcal{D}}(G_2) = -9$$

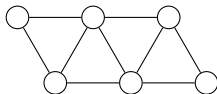


$$\det_{\mathcal{D}}(G_3) = -9$$

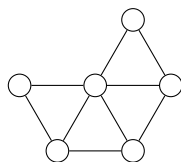
How about k -trees?



$$\det_{\mathcal{D}}(G_1) = -8$$



$$\det_{\mathcal{D}}(G_2) = -9$$



$$\det_{\mathcal{D}}(G_3) = -9$$

Linear 2-trees seems promising.

Linear 2-trees

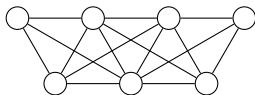
A **linear k -tree** is a graph obtained from K_{k+1} by adding a vertex each time and join it to the previously added vertex and $k - 1$ of its neighbors.

Theorem (Cheng and L 2018+)

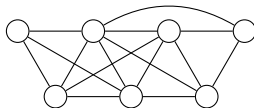
For every linear 2-tree G on n vertices,

$$\det_{\mathcal{D}}(G) = (-1)^{n-1} \left(1 + \left\lfloor \frac{n-2}{2} \right\rfloor \right) \left(1 + \left\lceil \frac{n-2}{2} \right\rceil \right).$$

How about linear k -tree?



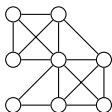
$$\det_{\mathcal{D}}(G_1) = 4$$



$$\det_{\mathcal{D}}(G_2) = 6$$

2-clique paths

Given $p_1, \dots, p_m \geq 3$, a **2-clique path** is obtained from a sequence of complete graphs K_{p_1}, \dots, K_{p_m} by gluing an edge of K_{p_i} to an edge of $K_{p_{i+1}}$, $i = 1, \dots, m$; an edge cannot be glued twice. The family $\mathcal{CP}_{2:p_1, \dots, p_m}$ collects all such graphs.



$$G \in \mathcal{CP}_{2:3,4,3,4}$$

$$\det_{\mathcal{D}}(G) = (1 + 1 + 1)(1 + 2 + 2) = 15$$

Theorem (Cheng and L 2018+)

For every graph $G \in \mathcal{CP}_{2:p_1, \dots, p_m}$ on n vertices,

$$\det_{\mathcal{D}}(G) = (-1)^{n-1} \left(1 + \sum_{k \text{ odd}} (p_k - 2) \right) \left(1 + \sum_{k \text{ even}} (p_k - 2) \right).$$

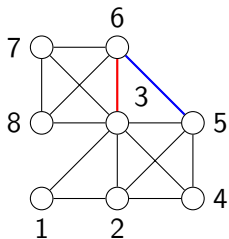
Alternative way to construct a 2-clique path

- ▶ Decide the backward degree q_1, \dots, q_n ; e.g. $0, 1, 2, 2, 3, 2, 2, 3$
- ▶ Define $b_k = k - q_k + 1$ so that

$$[b_k, k - 1] = \{b_k, \dots, k - 1\}$$

are the previous $q_k - 1$ vertices before k .

- ▶ Start with K_2 on vertices 1 and 2. For $k = 3, \dots, n$, add a new vertex k , then join it with the $q_k - 1$ vertices in $[b_k, k - 1]$ and **another neighbor** a_k of $k - 1$.



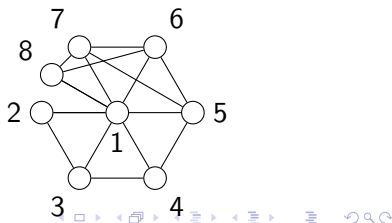
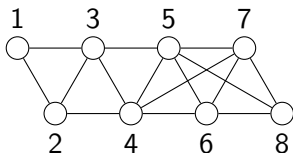
$$k = 6, q_k = 2$$

$$b_k = 5, [b_k, k - 1] = \{5\}$$

$$a_k \text{ can be chosen from } \{2, 3, 4\}$$

The CP graphs

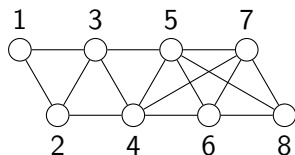
- ▶ A sequence $0, 1, q_3, \dots, q_n$ is called a **non-leaping** sequence if $2 \leq q_k \leq q_{k-1} + 1$ for $k \geq 3$. (So $q_3 = 2$ if $n \geq 3$.)
- ▶ The **CP graphs** $\mathcal{CP}_{q_1, \dots, q_n}$ consists of any graphs constructed by the following way:
 - ▶ $b_k = k - q_k + 1$ so that $[b_k, k - 1]$ has $q_k - 1$ elements.
 - ▶ Start with K_2 on vertices 1 and 2. For $k = 3, \dots, n$, add a new vertex k , then join it with the $q_k - 1$ vertices in $[b_k, k - 1]$ and **another neighbor** a_k of $k - 1$.
- ▶ Examples of $\mathcal{CP}_{0,1,2,2,2,2,3,3}$:



Reducing matrix

- ▶ The **reducing matrix** E of a CP graph is an $n \times n$ matrix whose k -th column is

$$\begin{cases} \mathbf{e}_k & \text{if } k \in \{1, 2\}, \\ \mathbf{e}_k - \mathbf{e}_{a_k} - \mathbf{e}_{k-1} + \mathbf{e}_{a_{k-1}} & \text{if } k \geq 3. \end{cases}$$



$$\begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Theorem (Cheng and L 2018+)

Let s be a non-leaping sequence. For any $G \in \mathcal{CP}_s$ with the distance matrix \mathcal{D} and the reducing matrix E , the matrix

$$E^T \mathcal{D} E$$

only depends on s .

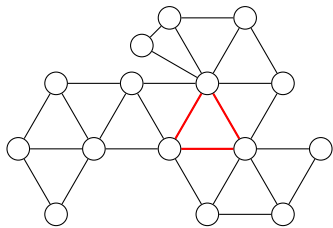
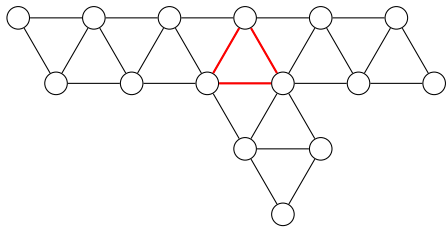
- ▶ Note that E is an upper triangular matrix with every diagonal entry equal to 1.

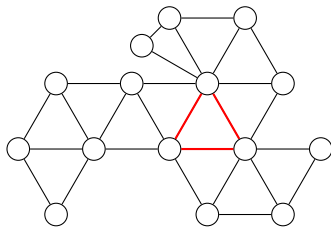
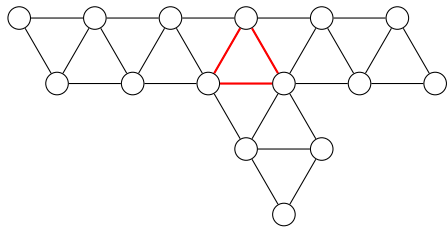
Corollary (Cheng and L 2018+)

Let s be a non-leaping sequence. Then

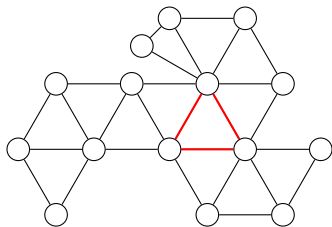
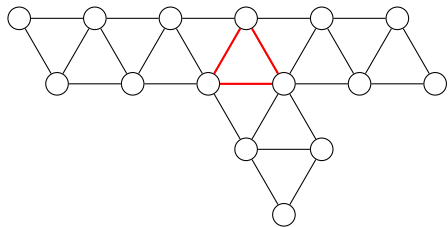
$$\det_{\mathcal{D}}(G) \text{ and } \text{inertia}_{\mathcal{D}}(G)$$

are independent of the choice of $G \in \mathcal{CP}_s$.








$$\det_{\mathcal{D}}(G_1) = \det_{\mathcal{D}}(G_2) = 56$$






$$\det_{\mathcal{D}}(G_1) = \det_{\mathcal{D}}(G_2) = 56$$

Thank you!

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